

OPERATION INSTRUCTONS

MODEL SA 07.1 - SA 48.1

Multi-Turn Actuators

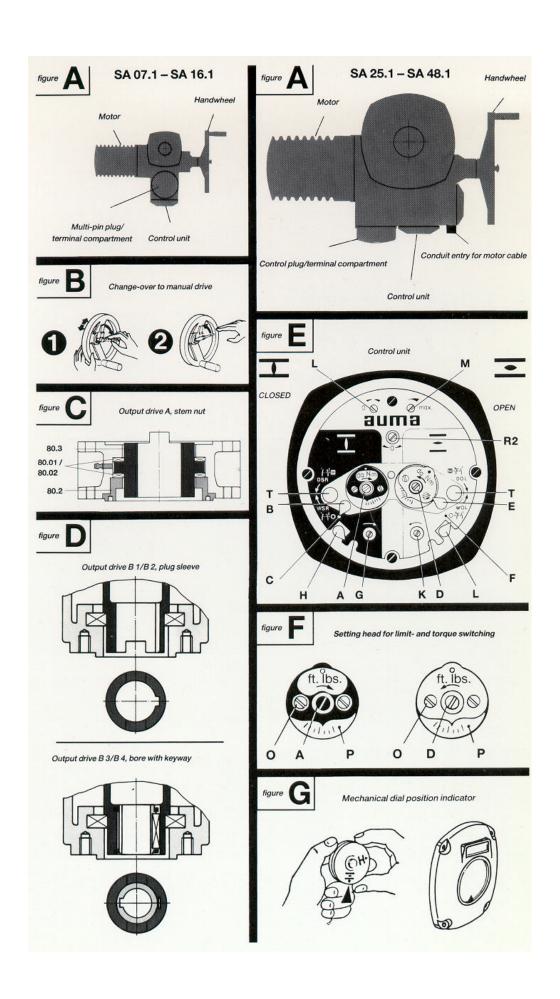


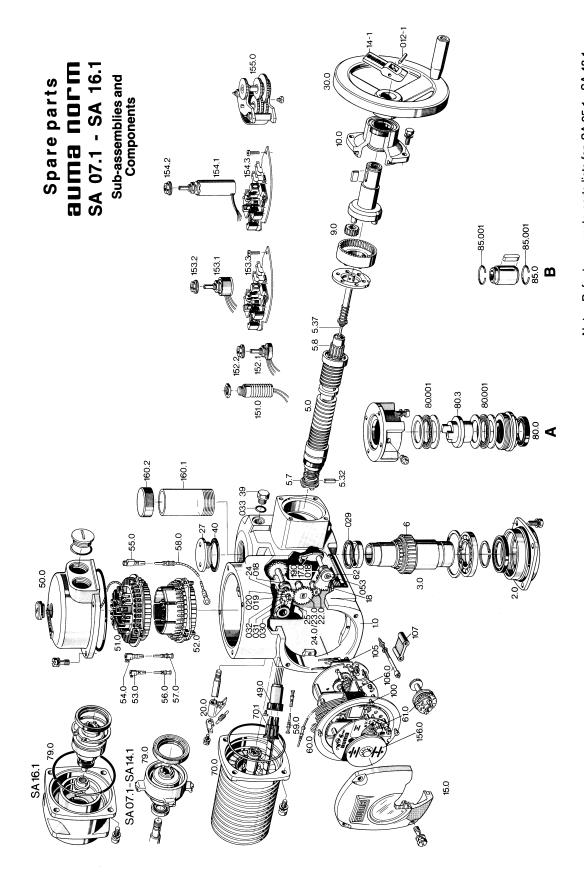
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www.auma-usa.com email: mailbox@auma-usa.com This operation instruction is valid for the types: SA, SA(IP68), SAL, SAEL, SAH, SAR, SAFM, SARFM, SAEx, SAREx.

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Note: Refer to separate parts lists for SA 25.1 - SA 48.1

Multi-turn actuators are high quality electro-mechanical devices. Possible damage can be avoided by observing the following items.

1. TRANSPORT AND STORAGE

- Transport to place of installation in sturdy packing.
- Do not lift the actuator by the handwheel.
- Store in well ventilated, dry room.
- Protect against humidity from the floor by storing on a shelf or on a wooden frame.
- Cover to protect against dust and dirt.
- Apply corrosion protection agent to machined surfaces.

2. SERVICE CONDITIONS

AUMA multi-turn actuators can be used at following ambient conditions:

Model	Temperature
SA	-20°F to +175°F (Standard)
SAL	-40°F to +140°F
SAH	+32°F to +250°F
SA(IP68)	-20°F to +175°F
SAR	-20°F to +140°F

3. MOUNTING TO THE VALVE/GEARBOX

Mounting and operation can be in any position.

Check whether output drive flange suits the valve/gearbox.

CAUTION: Spigot at flanges should be loose fit!

- For form A output drive the thread must correspond with thread of the valve stem. If not
 ordered explicitly with thread, the stem nut is supplied unbored or with pilot bore (*Figure C*).
 For machining the stem nut refer to Section 13.
- Form B output drives are normally supplied with bore and one keyway (Figure D).
- Check whether bore and keyway correspond with the input shaft of the valve or gearbox.
- Degrease mounting surfaces at actuator and valve/gearbox thoroughly.
- Apply lubricant to input shaft of the valve/gearbox.
- Place actuator on the valve/gearbox and use bolts with a minimum quality of 8.8 to fasten. Tighten diagonally.

4. MANUAL OPERATION

Engaging Handwheel (*Figure B*)

CAUTION: Manual operation should not be engaged if motor is running.

- Lift declutch lever in center of handwheel to fully extended position while slightly turning the handwheel.
- Release declutch lever, it must snap back to its original position; manual mode remains engaged.

Manual Operation

WARNING •

DECLUTCH LEVER MUST BE FULLY RELEASED AND RETURNED TO UNENGAGED POSITION (90°) WHILE IN MANUAL HANDWHEEL OPERATION TO PREVENT PHYSICAL DAMAGE.

- If power tools are used, the permissible speed is 300 rpm.
- For two-inch nut or chainwheel operation refer to separate instructions.

Disengaging Manual Operation

Manual drive disengages automatically when motor is started.

5. ELECTRICAL CONNECTIONS

CAUTION: Observe safety regulations. Check whether the power supply (voltage, phase and frequency) complies with the motor nameplate.

Terminal Access

- Take off the terminal compartment cover.
- Loosen cheese head screws inside the cover and remove multi socket carrier.

- Check the location of the terminal connections.
 - For SA 07.1 SA 16.1 motor power is connected in center of socket carrier.
 - For SA 25.1 SA 48.1 motor power is connected in separate conduit entry (*Figure A*).
 - For SA 07.1 SA 48.1 control power is connected to sockets in socket carrier.
- Attach conduit to terminal compartment cover.

CAUTION: Appropriate conduit and sealing methods must be followed to ensure the type of enclosure furnished.

Wiring Connections - Refer to drawing inside terminal compartment cover

NOTE: The drawing contains the required information for correct actuator electrical connection. Typical customer controls are also shown.

- Connect motor wires to the designated terminals. Connect ground to designated terminal.
- Connect control wires to designated terminals in accordance with drawing.

CAUTION: The following must be considered when wiring an AUMA actuator:

- ◆ The time delay (i.e., from limit or torque switch tripping until the motor is switched off) should not exceed 20 ms. We strongly recommend switching off the motor directly by installing the corresponding switches in the control wiring to the contactor. This concern is especially important when using PLC's. Switch output to a PLC should be for indication only.
- ♦ Each switch has contacts which are not completely isolated and therefore are suitable only for the same voltage potential. (See drawing for detailed information.)
- ◆ The valve manufacturer decides whether switching off in the end position should be by limit switch (limit seating) or torque switch (torque seating).
- ♦ AUMA motors have 3 thermoswitches as standard equipment. These switches must be directly wired into the control circuit to protect the motor. If these are not connected, the warranty for the motor is not valid.

Completion of Electrical Connection

• Clean the sealing faces at plug or cover for terminal compartment, check to ensure that the O-ring is not damaged.

- Apply a thin film of non-acid grease (e.g., Vaseline) to sealing faces.
- Place cover and fasten the 4 bolts. Tighten diagonally.

CAUTION: NEMA 7 enclosures require that a conduit seal be placed as close as practicable to the conduit entries at the actuator.

6. TEST RUN (*Figure E*)

Remove cover to the control unit compartment (15.0) and, if provided, the MDPI disc (156.0).

- Bring the valve manually to an intermediate position.
- Check phase rotation.
- Run the actuator briefly in the open direction. If the direction of rotation is incorrect, switch off immediately and rewire motor connections U1 and W1.
- The red test knobs on the control unit provide a way to manually operate the limit and torque switches.

While running the actuator in the open direction, turn the red test knob OPEN toward the DOL arrow.

- ♦ If the motor stops, the control circuit is correct.
- ◆ If the motor does not stop, turn off the motor power immediately. Check control circuit and correct wiring.

Operating Direction for Test Knobs

	Torque Switch	Limit Switch
open	DOL Arrow	WOL Arrow
close	DSR Arrow	WSR Arrow

 Determine overrun in both directions (overrun is turns/travel from switching off until the actuator movement stops.

The convention of "clockwise-to-close" has been used throughout this manual. A "clockwise-to-open" valve or damper configuration represents a reversal of limit and torque switch position (black area

of face plate of the control unit represents open and white area represents closed.)

7. **SETTING OF LIMIT SWITCHING** (*Figure E*)

Engage manual drive as explained in Section 4.

Setting of the CLOSED End Position (black area)

- Turn the handwheel clockwise until the valve is fully closed. Consider possible overrun as described in Section 6.
- Press down and turn spindle (A) in direction of the arrow. A ratchet will be felt and heard, the pointer (B) turns for every 90 degrees.

When pointer moves towards point (C), the spindle should not be turned any further. If the spindle has been turned beyond that point inadvertently, continue turning and approach the setting point again.

CAUTION: Make sure that spindle (A) springs up to its original position.

Setting of the OPEN End Position (white area)

- Turn the handwheel counter-clockwise until the valve is fully open. Consider possible overrun as determined in Section 6. Compensate overrun by backing off with the manual drive.
- Repeat setting procedure as described for the closed position using spindle (D), pointer (E) and point (F).

8. SETTING OF DUO COUNTER GEAR OR FOUR GEAR TRAIN LIMIT SWITCHING (optional) (Figure E)

CAUTION: The intermediate switching point should be approached for setting purposes in the same direction as in motor operation.

- Move valve to the required intermediate position.
- For switching in the direction CLOSED (LSA) use spindle (G), pointer (H) and point (C) as explained previously.
- For switching in the direction OPEN (LSB) use spindle (K), pointer (L) and point (F) as explained previously.

9. **SETTING OF TORQUE SWITCHING** (*Figure F*)

CAUTION: Adjusted torque must suit the valve! If the actuator has been supplied by a valve manufacturer, this setting was made during testing. This setting should only be changed with the consent of the valve manufacturer.

- Loosen both lock screws (O) at torque dial.
- Rotate torque dial (P) to the required setting (1 ft. lbs. equals 1.36 Nm).
- Fasten lock screw again.

NOTE: Torque switching works in both manual and electrical mode. The torque switching acts as overload protection over full travel as well as at the end positions.

- Clean sealing surfaces at the housing and the switch compartment cover (3.2). Check the O-ring for possible damage. Apply thin film of non-acid grease (e.g. Vaseline) to sealing faces.
- Place the cover and fasten the hexagonal bolts. Tighten diagonally.

10. SETTING OF MECHANICAL DIAL POSITION INDICATOR - optional (Figure G)

The indicator disc rotates approximately 180 degrees at full travel from OPEN to CLOSE or vice versa.

A suitable reduction gearing was installed in our factory. If turns per stroke are changed subsequently, the reduction gearing may have to be exchanged, too.

- Run actuator to the CLOSED end position.
- Turn dial \(\pi\) CLOSED until the arrow is in alignment with the mark on the indicator glass.
- Run Actuator to the OPEN end position.

11. SETTING OF THE POTENTIOMETER (optional) (*Figure E*)

Operate valve to the CLOSED position.

Set the potentiometer to the initial position (minimum resistance) by turning spindle (R2).

12. SETTING OF THE CURRENT TRANSMITTER RWG (optional) (Figure E)

Adjustments for 4 mA to close and 20 mA to open

- Run the actuator to the full closed position, and adjust the feedback potentiometer (R2) to the full clockwise end position. (Note: counter-clockwise for counter-clockwise-to-close actuators).
- Adjust zero adj. potentiometer (L) clockwise until the desired current output for the closed position is obtained (normally 4 mA). Turn potentiometer clockwise to increase current output, counterclockwise to decrease.
- Run actuator to the full open position.
- Adjust max adj. potentiometer (M) until the desired current output for the open position is obtained (normally 20 mA). Turn potentiometer clockwise to increase current output, counter-clockwise to decrease.
- Run actuator to the full closed position to check the closed position current output.
- If necessary, readjust the zero adj. potentiometer to the value obtained in Step 3 and repeat Steps 4 through 6. Otherwise, the procedure is complete.

NOTE: The adjustment of the zero adj. and max adj. potentiometers is an interactive process and may require that the potentiometers are adjusted a number of times.

NOTE: For other settings, please refer to separate setting instructions.

13. MACHINING OF STEM NUT, FORM A OUTPUT DRIVE (Figure C)

Mounting flange does not need to be taken off the actuator.

- Remove the bearing lock nut (80.2) using a wrench or similar tool.
- Take off the stem nut (80.3), thrust bearing (80.01) and thrust bearing races (80.02).
- Remove the thrust bearing and races from stem nut.
- Drill and bore the stem nut, cut the thread.

CAUTION: When fixing in the chuck make sure the stem nut runs true.

- Clean the machined stem nut.
- Apply ball bearing grease to the thrust bearing and races and place them on the stem nut.
- Put the stem nut into the mounting flange. Be careful that the dogs are placed correctly in the slots
 of the hollow shaft.

- Screw in the bearing lock nut until it is firm against the shoulder.
- The A drive housing is provided with a grease nipple for lubrication. Ensure that an adequate amount of grease is provided for proper operation. Frequency of lubrication must be determined according to usage. Contact the factory for further information on output drives.

14. MAINTENANCE

AUMA Actuators need little maintenance. A precondition for reliable service is correct commissioning and start up. It is also very important that the O-rings for the covers are placed correctly, and conduit entries are fastened firmly to prevent the ingress of dirt or water.

We recommend:

- If operated very seldom, perform a test run every six (6) months. This assures that the actuator is always ready to operate.
- Approximately six (6) months after start-up and then every year check the bolts between the actuator and the valve/gearbox for tightness. If required, retighten.
- Multi-turn actuators with Form A output drive must be lubricated at intervals of approximately six (6) months, using the grease nipple.

CAUTION: Lubrication of the valve stem must be done separately.

This operation instruction has been prepared to the best of our knowledge in order to inform our customers. It is the result of our practical experience and extensive testing.

Our multi-turn actuators were designed principally for the operation of valves. Before using them for other purposes, we recommend examining whether our products perform the functions desired. Further knowledge about their suitability may be obtained by tests. We are prepared to assist in the performance of these tests.

For special applications please consult factory.

When using our multi-turn actuators for applications not intended by us, we cannot be held responsible. Necessary precautions to prevent injury to persons or damage to materials are the sole responsibility of the user.

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Actuators* with the BASIC COMPACT and AUMA MATIC contain pilot devices and complete motor controls. The controls are contained in a sealed housing, which is mounted directly to actuators of the version, AUMA NORM.

Electrical connections between the BASIC COMPACT or AUMA MATIC unit and actuator are made by plug/socket. This enables the BASIC COMPACT or AUMA MATIC unit to be fitted to the type AUMA Norm actuators already installed.

^{*}Available in sizes SA 07.01 — SA 16.1

For professional start-up and reliable service in the field, AUMA has specialists in the factory for:

- Shipping of original spare parts
- Commissioning
- Maintenance/repair
- Trouble-shooting assistance

Before calling for our support, please have the following information:

- 1) For Parts:
 - Original S.O. Number or Serial Number of Actuator (on name tag)
 - Part Number (on exploded view)
- 2) For Service:
 - Original S.O. Number or Serial Number of Actuator
 - Brief Description of Problem

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All information is subject to change without notice.